

Bayesian network statistics

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Motivation

- How can we estimate the statistics for thermodynamic quantities without jeopardizing quantum coherences and correlations?
- How do initial correlations contribute to such statistics?
- Are there different possible estimations with different precision?

Background

Our estimations are made with the use of Bayesian Networks (BN)¹ in which we infer probabilities of events conditioned on previous events, eliminating the need for measurements in the construction of the distributions.

BNs and our setup

- Our setup consists of a global system with two parties A and B interacting via an unitary U ;
- If the global system starts with an initial state $\rho = \sum_i p_i |\psi_i\rangle \langle \psi_i|$, then the BN infer that the probability of the subsystem A start at the state $|a_0\rangle$ and evolve to $|a_t\rangle$ after the unitary evolution is

$$\mathcal{P}(a_t, a_0) = \sum_i p_i P(a_0|\psi_i) P(a_t|\psi_{i_t}),$$

where $P(a_0|\psi_i) = |\langle a_0|\psi_i\rangle|^2$ and $P(a_t|\psi_{i_t}) = |\langle a_t|U|\psi_i\rangle|^2$.

Results

➤ Given an observable \mathcal{A} in the subsystem A , we obtained the first two moments of its variation $\Delta\mathcal{A}$

$$\langle \Delta\mathcal{A} \rangle = \text{Tr} [\rho(U^\dagger \mathcal{A} U - \mathcal{A})]$$

and

$$\langle (\Delta\mathcal{A})^2 \rangle = \text{Tr} [\rho((U^\dagger \mathcal{A} U)^2 + A^2)] - 2 \sum_i p_i \langle \psi_i | A | \psi_i \rangle \langle \psi_i | U^\dagger \mathcal{A} U | \psi_i \rangle,$$

from the characteristic function

$$G(k) = \sum_i p_i \langle \psi_i | e^{-ik\mathcal{A}} | \psi_i \rangle \langle \psi_i | e^{ikU^\dagger \mathcal{A} U} | \psi_i \rangle.$$

■ Arbitrary ensemble choices in ρ infer different BN probability distributions. But the average of $\Delta\mathcal{A}$ is independent of the ensemble choice!

Heat in the bosonic case

➤ The parties A and B are single bosonic modes, U is the Beam Splitter (BS) interaction and \mathcal{A} is the local Hamiltonian of A , then $\Delta\mathcal{A} = Q$ is the heat exchanged by A . If initially the global covariance matrix is

$$\sigma_{AB} = \begin{pmatrix} a & 0 & c_+ & 0 \\ 0 & a & 0 & c_- \\ c_+ & 0 & b & 0 \\ 0 & c_- & 0 & b \end{pmatrix},$$

then the average heat will be

$$\langle Q \rangle = \omega [\sin^2(g)(b - a) + \sin(g) \cos(g)(c_+ + c_-)],$$

where g is the BS strength.

➤ Choosing the ensemble of coherent states for representing the density matrix, we arrive at a larger variance distribution than choosing the ensemble of eigenvectors of ρ .

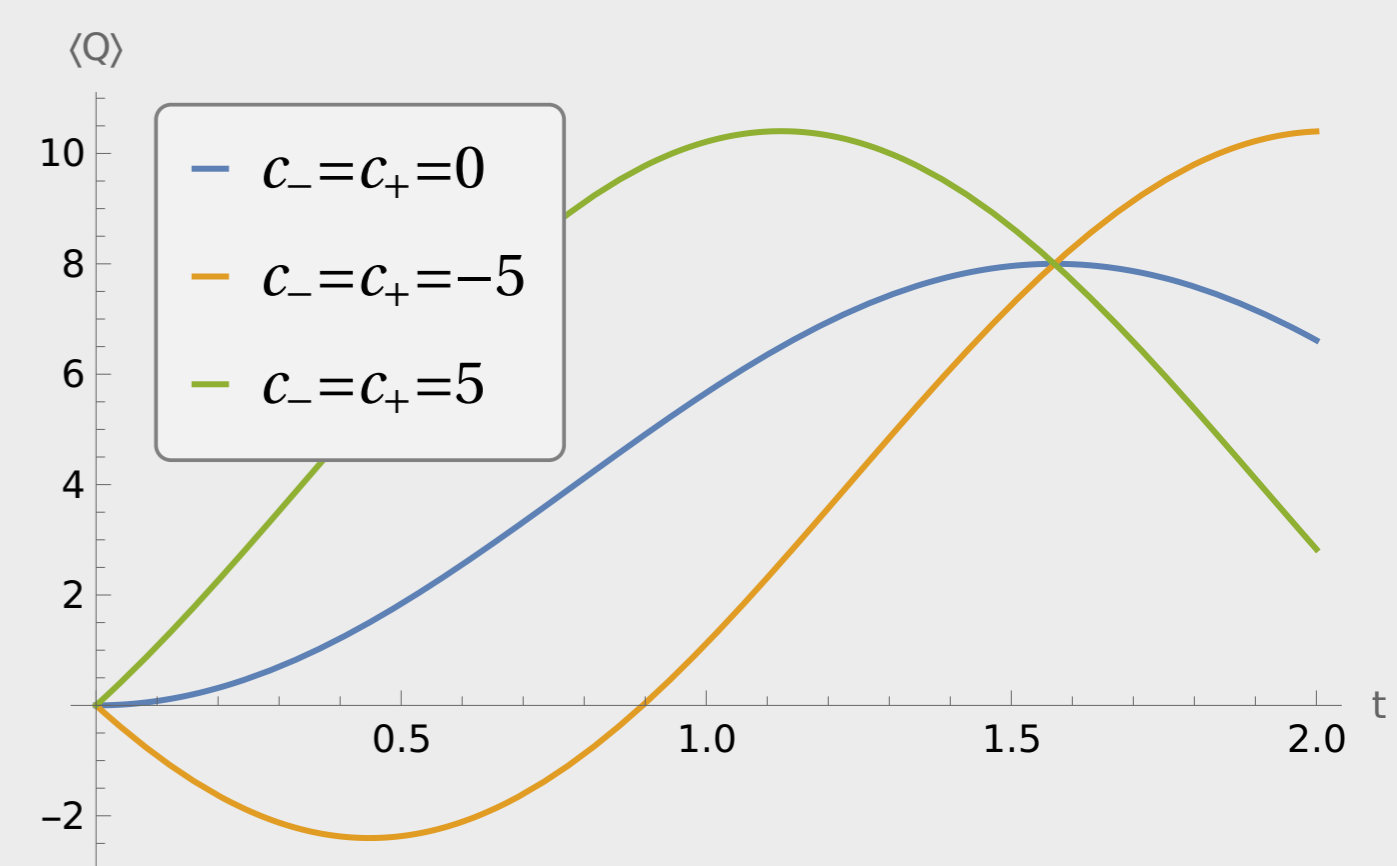


Figure 1: Average of heat for different choices of correlations (all with $a = 3$ and $b = 11$). For certain combinations of initial correlations, described by c_+ and c_- , we have the inversion of the heat flux.²

Conclusions and future perspectives

- ✓ The statistics sustain effects of the initial correlations, reproducing descriptions such as the inversion of heat flux,²
- ✍ The relation of higher moments for different ensemble choices remain unclear. The analysis of the bosonic heat case seems to suggest that the ensemble of eigenvectors of ρ is the one with least variance.

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References

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